

A Sequent Calculus For Trace Formula Implication

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Joint Work with Reiner Hähnle



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- **Trace formulas** are a novel logic that
 - ▣ specifies **whole sets of program traces**
 - ▣ can even specify recursive traces using **fixpoint operations**
 - ▣ allows the specification of
 - precisely all traces of simple imperative programs
 - abstract trace properties



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 - precisely all traces of simple imperative programs
 - abstract trace properties
- Verification if a program **satisfies** a trace formula requires trace formula **weakening**
- **Main Contribution:** Calculus for Trace Formula Implication

Connection Between Programs and Formulas

by Gurov & Hähnle, FSCD, 2025



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For every Rec program P , there exists a **strongest trace formula** that specifies **precisely** the traces generated by P .



A **Rec Program** is a tuple (S, T) using **global variables only**, where

- S is a statement generated by

$$S ::= \text{skip} \mid x := a \mid S; S \mid \text{if } b \text{ then } S \text{ else } S \mid m()$$

- T is a sequence of parameter-less methods $m\{S\}$ consisting of name m and body S

Example

$$S_d := \text{down}() \text{ with } T_d := \text{down} \{ \text{if } x = 0 \text{ then skip else } x := x - 1; \text{down}() \}$$



Trace Formulas are a finite trace specification logic generated by

$$\Phi ::= p$$

- A **unary predicate** p semantically maps to all finite traces which satisfy p in its initial state:

$$\llbracket p \rrbracket_{\mathbf{v}} = \{s \cdot \sigma \mid s \models p \wedge \sigma \in \text{State}^*\}$$

Example

$\mathbf{x} = \mathbf{0}$ specifies all traces satisfying $\mathbf{x} = \mathbf{0}$ in its first state.



Trace Formulas are a finite trace specification logic generated by

$$\Phi ::= p \mid R$$

- A **binary relation** R semantically maps to all binary traces included in R :

$$\llbracket R \rrbracket_{\mathbb{V}} = \{s \cdot s' \mid R(s, s')\}$$

Common Relations

Id (Identity) and **Sb_x^a** (Update) are common relations:

$$(s, s') \in \mathbf{Id} \iff s = s' \qquad (s, s') \in \mathbf{Sb}_x^a \iff s' = s[x \mapsto \text{eval}_s(a)]$$

Trace Formulas

Conjunctions and Disjunctions



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Trace Formulas are a finite trace specification logic generated by

$$\Phi ::= p \mid R \mid \Phi \wedge \Phi \mid \Phi \vee \Phi$$

- **Conjunctions/Disjunctions** map to the intersection/union of the composite specified traces:

$$\llbracket \Phi_1 \wedge \Phi_2 \rrbracket_{\mathbf{v}} = \llbracket \Phi_1 \rrbracket_{\mathbf{v}} \cap \llbracket \Phi_2 \rrbracket_{\mathbf{v}}$$

$$\llbracket \Phi_1 \vee \Phi_2 \rrbracket_{\mathbf{v}} = \llbracket \Phi_1 \rrbracket_{\mathbf{v}} \cup \llbracket \Phi_2 \rrbracket_{\mathbf{v}}$$

Example

$\mathbf{x} = \mathbf{0} \wedge \mathbf{Id}$ is a trace formula specifying all traces of length 2 with $\mathbf{x} = \mathbf{0}$ in both states.

Trace Formulas are a finite trace specification logic generated by

$$\Phi ::= p \mid R \mid \Phi \wedge \Phi \mid \Phi \vee \Phi \mid \Phi \frown \Phi$$

- The **chop** joins the traces of two trace formulas sequentially:

$$\llbracket \Phi_1 \frown \Phi_2 \rrbracket_{\mathbf{V}} = \{ \sigma_1 \cdot s \cdot \sigma_2 \in P(\text{State}^+) \mid \sigma_1 \cdot s \in \llbracket \Phi_1 \rrbracket_{\mathbf{V}} \wedge s \cdot \sigma_2 \in \llbracket \Phi_2 \rrbracket_{\mathbf{V}} \}$$

- Originates from Temporal Interval Logic

Example

$\text{Id} \frown \text{Id}$ is a trace formula specifying all unchanging traces of length 3.



Trace Formulas are a finite trace specification logic generated by

$$\Phi ::= p \mid R \mid \Phi \wedge \Phi \mid \Phi \vee \Phi \mid \Phi \frown \Phi \mid \textcolor{blue}{X} \mid \textcolor{blue}{\mu}X.\Phi$$

- The **free recursive variable** $\textcolor{blue}{X}$ maps according to valuation $\mathbb{V} : RVar \rightarrow P(State^+)$
- The **fixpoint operator** maps to the least fixpoint of Φ , i.e. its minimal recursive traces:

$$\llbracket \mu X.\Phi \rrbracket_{\mathbb{V}} = \bigcap \{ \gamma \subseteq State^+ \mid \llbracket \Phi \rrbracket_{\mathbb{V}[X \mapsto \gamma]} \subseteq \gamma \}$$

Example

$\mu X.(R \vee R \frown X)$ is a trace formula modeling the transitive closure of relation R .

Trace Formulas

Fixpoint Operator: Demonstration



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$$\llbracket \mu X. \Phi \rrbracket_{\forall} = \bigcap \{ \gamma \subseteq \text{State}^+ \mid \llbracket \Phi \rrbracket_{\forall[X \mapsto \gamma]} \subseteq \gamma \}$$

$\llbracket \mu X. (\mathbf{Sb}_y^{y+1} \vee \mathbf{Sb}_y^{y+1} \frown X) \rrbracket_{\forall}$ specifies the following traces:

- $([y \mapsto 5], [y \mapsto 6])$
- $([y \mapsto 4], [y \mapsto 5], [y \mapsto 6])$
- $([y \mapsto 3], [y \mapsto 4], [y \mapsto 5], [y \mapsto 6])$
- $([y \mapsto 0], [y \mapsto 1], \dots, [y \mapsto 2024], [y \mapsto 2025])$
- and many more...



Note that $\forall$ is irrelevant, as the formula is closed.

Unique Characteristics of Trace Formulas



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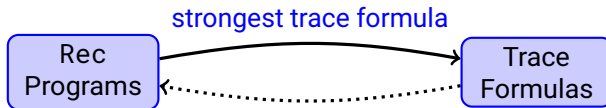
The most important characteristics of trace formulas are the support of

1. the **chop-operator** $\Phi_1 \frown \Phi_2$
⇒ difference to μ -calculus
2. the **fixpoint-operator** $\mu X. \Phi$
⇒ modeling of recursive traces using fixpoints

! Related logics typically go either

- without the chop, or
- without the fixpoint

Strongest Trace Formulas: Concept



Example

The **strongest trace formula** of S_{down} is $stf(S_{down})$:

$S_{down} := \text{down}() \text{ with } down \{ \text{if } x = 0 \text{ then skip else } x := x - 1; \text{down}() \}$

$stf(S_{down}) := Id \frown \mu X_{down}. ((x = 0 \wedge Id \frown Id) \vee (x \neq 0 \wedge Id \frown Sb_x^{x-1} \frown Id \frown X_{down}))$

Strongest Trace Formulas: Main Theorem

by Gurov & Hähnle, FSCD, 2025



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A program S **satisfies** a closed trace formula Φ iff $\text{traces}(S) \subseteq \llbracket \Phi \rrbracket$.

$\text{traces}(S) \subseteq \llbracket \Phi \rrbracket$

iff

$\text{stf}(S) \models \Phi$

S **satisfies** (abstract) property Φ

$\text{stf}(S)$ **implies** (abstract) property Φ



Reduction to **Trace Formula Implication Problem**.

Main Contribution: Calculus for Trace Formula Implication

Sequents

First Idea of a Sequent Definition



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- Shape of a **sequent**:

$$\Gamma \vdash \Delta$$

Γ and Δ sets of *arbitrary trace formulas*

- A sequent $\Gamma \vdash \Delta$ is called **valid** iff

$$\bigwedge \Gamma \models \bigvee \Delta$$

i.e. $\llbracket \bigwedge \Gamma \rrbracket_{\mathbb{V}} \subseteq \llbracket \bigvee \Delta \rrbracket_{\mathbb{V}}$ for any arbitrary valuation $\mathbb{V}$



Sequents are interpreted relative to current state.



- **Current state information** of antecedent Γ :

$$P_{\Gamma} := \{p \in \Gamma \mid p \in \text{Pred}\}$$

- The **predicate rule** infers additional information about the current state and adds it to the antecedent:

$$\text{PRED} \frac{\Gamma, \mathbf{q} \vdash \Delta}{\Gamma \vdash \Delta} \wedge P_{\Gamma} \rightarrow \mathbf{q}$$



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Example

$$\text{PRED} \frac{x > 0, x < 0, \mathbf{false} \vdash \Delta}{x > 0, x < 0 \vdash \Delta} \mathbf{x > 0 \wedge x < 0 \rightarrow false}$$

Calculus Rules

Chop Rules: Identity (Simplified Variant)



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- In the case of id , the current state information P_Γ is **preserved**.

$$\text{CH-ID} \frac{P_\Gamma, id \vdash \psi \quad P_\Gamma, \phi \vdash \psi'}{\Gamma, id \frown \phi \vdash \psi \frown \psi', \Delta}$$

- Information about Γ and Δ is lost in simplified variant.

Calculus Rules

Chop Rules: Identity (Simplified Variant)



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- In the case of ld , the current state information P_Γ is **preserved**.

$$\text{CH-ID} \frac{P_\Gamma, ld \vdash \psi \quad P_\Gamma, \phi \vdash \psi'}{\Gamma, ld \frown \phi \vdash \psi \frown \psi', \Delta}$$

- Information about Γ and Δ is lost in simplified variant.

Example

$$\text{CH-ID} \frac{x = 0, ld \vdash ld \quad x = 0, ld \vdash ld}{x = 0, ld \frown ld \vdash ld \frown ld}$$

Calculus Rules

Chop Rules: Update (Simplified Variant)



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- In case of Sb_x^a , the current state information P_Γ is modified to the **strongest postcondition**.

$$\text{CH-UPD} \frac{P_\Gamma, Sb_x^a \vdash \psi \quad spc_{x:=a}(P_\Gamma), \phi \vdash \psi'}{\Gamma, Sb_x^a \frown \phi \vdash \psi \frown \psi', \Delta}$$

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Calculus Rules

Chop Rules: Update (Simplified Variant)



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- Information about Γ and Δ is lost in simplified variant.

Example

$$\text{CH-UPD} \frac{x = 0, Sb_x^1 \vdash Sb_x^1 \quad x = 1, Id \vdash Id}{x = 0, Sb_x^1 \wedge Id \vdash Sb_x^1 \wedge Id}$$



- We can **unfold** fixpoint operators $\mu X.\Phi$ into the semantically equivalent formula $\Phi[\mu X.\Phi/X]$.
- **Unfolding rules** can unfold fixpoint formulas in the antecedent and succedent:

$$\text{UNFL} \quad \frac{\Gamma, \Phi[\mu X.\Phi/X] \vdash \Delta}{\Gamma, \mu X.\Phi \vdash \Delta}$$

$$\text{UNFR} \quad \frac{\Gamma \vdash \Psi[\mu X.\Psi/X], \Delta}{\Gamma \vdash \mu X.\Psi, \Delta}$$



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Example

$$\text{UNFR} \quad \frac{\Gamma \vdash R \vee R \frown \mu X.(R \vee R \frown X)}{\Gamma \vdash \mu X.(R \vee R \frown X)}$$

The Problem with Unfoldings



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Let us assume a sequent of the shape $\mu X_1. \Phi \vdash \mu X_2. \Psi$.

- Unfolding strategy of $\mu X_1. \Phi$ **not always applicable**, as the amount of needed unfolding steps can be very large or may even be unbounded.

Example (down cont.)

$$\text{Sb}_x^{10} \frown \text{Id} \frown \mu X_{\text{down}}. ((x = 0 \wedge \text{Id} \frown \text{Id}) \vee (x \neq 0 \wedge \text{Id} \frown \text{Sb}_x^{x-1} \frown \text{Id} \frown X_{\text{down}})) \vdash \Delta$$

$\Rightarrow$ Unfolding strategy *possible*

$$\text{Id} \frown \mu X_{\text{down}}. ((x = 0 \wedge \text{Id} \frown \text{Id}) \vee (x \neq 0 \wedge \text{Id} \frown \text{Sb}_x^{x-1} \frown \text{Id} \frown X_{\text{down}})) \vdash \Delta$$

$\Rightarrow$ Unfolding strategy *impossible*

Sequents

Adapted Sequent Definition



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■ **Objective:** Show $\mu X_1. \Phi \vdash \mu X_2. \Psi$

⇒ **Solution:** Create a **connection between the recursive variables** of both fixpoints.



- **Objective:** Show $\mu X_1. \Phi \vdash \mu X_2. \Psi$
 $\implies$ **Solution:** Create a **connection between the recursive variables** of both fixpoints.
- A **recursive variable assumption set** ξ is a set of tuples of the shape $(\mathbf{X}_1|_{\text{Inv}}, \mathbf{X}_2)$.
It is called **valid** in $\mathbb{V}$ iff for all its tuples $(\mathbf{X}_1|_{\text{Inv}}, \mathbf{X}_2)$, it holds that

$$\llbracket \mathbf{X}_1 \wedge \text{Inv} \rrbracket_{\mathbb{V}} \subseteq \llbracket \mathbf{X}_2 \rrbracket_{\mathbb{V}}$$



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- Adapted shape of a **sequent**:

$$\xi \diamond \Gamma \vdash \Delta$$



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- A sequent $\xi \diamond \Gamma \vdash \Delta$ is called **valid** iff

$$\llbracket \bigwedge \Gamma \rrbracket_{\mathbb{V}} \subseteq \llbracket \bigvee \Delta \rrbracket_{\mathbb{V}} \text{ for any arbitrary valuation } \mathbb{V} \text{ that is valid for } \xi$$



- The **fixpoint induction rule** first establishes that the **invariant** holds in current state P_Γ and then shows that the **invariant** is preserved to all recursive calls:

$$\text{FPI} \frac{P_\Gamma \vdash \text{Inv} \quad \xi, (\mathbf{X}_1|_{\text{Inv}}, \mathbf{X}_2) \diamond \text{Inv}, \Phi \vdash \Psi}{\xi \diamond \Gamma, \mu X_1. \Phi \vdash \mu X_2. \Psi, \Delta}$$



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Example

$$\text{FPI} \frac{x = 10 \vdash x > 0 \quad (\mathbf{X}_1|_{x>0}, \mathbf{X}_2) \diamond x > 0, Sb_x^{x+1} \vee Sb_x^{x+1} \frown \mathbf{X}_1 \vdash R_{pos} \vee R_{pos} \frown \mathbf{X}_2}{x = 10, \mu X_1. (Sb_x^{x+1} \vee Sb_x^{x+1} \frown \mathbf{X}_1) \vdash \mu X_2. (R_{pos} \vee R_{pos} \frown \mathbf{X}_2)}$$

- We then infer the trace inclusion between recursive variables based on ξ :

$$\text{RVAR} \frac{P_r \vdash \text{Inv}}{\xi, (\mathbf{X}_1 |_{\text{Inv}}, \mathbf{X}_2) \diamond \Gamma, \mathbf{X}_1 \vdash \mathbf{X}_2, \Delta}$$

- We then infer the trace inclusion between recursive variables based on ξ :

$$\text{RVAR} \frac{P_{\Gamma} \vdash \text{Inv}}{\xi, (\mathbf{X}_1|_{\text{Inv}}, \mathbf{X}_2) \diamond \Gamma, \mathbf{X}_1 \vdash \mathbf{X}_2, \Delta}$$

Example

$$\text{CH-UPD} \frac{\begin{array}{c} \vdots \\ \mathbf{x} > 0, \text{Sb}_x^{\mathbf{x}+1} \vdash R_{\text{pos}} \end{array} \quad \text{RVAR} \frac{\mathbf{x} > 1 \vdash \mathbf{x} > 0}{(\mathbf{X}_1|_{\mathbf{x} > 0}, \mathbf{X}_2) \diamond \mathbf{x} > 1, \mathbf{X}_1 \vdash \mathbf{X}_2}}{(\mathbf{X}_1|_{\mathbf{x} > 0}, \mathbf{X}_2) \diamond \mathbf{x} > 0, \text{Sb}_x^{\mathbf{x}+1} \neg \mathbf{X}_1 \vdash R_{\text{pos}} \neg \mathbf{X}_2}$$

Incompleteness of the Calculus

Method Contracts



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So far, we can only handle **tail recursive** occurrences of recursive variables or fixpoint operations. We lack rules otherwise:

$$\mathbf{x} = \mathbf{10}, X_1 \frown \Phi \vdash X_2 \frown \Psi$$



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$$\mathbf{x} = \mathbf{10}, X_1 \frown \Phi \vdash X_2 \frown \Psi$$

Solution: Method Contracts

- Employment of a rule that **proves** and a rule that **applies** a method contract.
- A method contract (**pre**, **post**) is *valid* for Φ in $\mathbb{V}$ iff

$$\llbracket \bigwedge v_{old}^i = v^i \wedge \mathbf{pre} \wedge \Phi \frown \mathbf{true} \rrbracket_{\mathbb{V}} \subseteq \llbracket \Phi \frown \mathbf{post} \rrbracket_{\mathbb{V}}$$

Incompleteness of the Calculus

Synchronization



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There are no rules that can perform fixpoint induction on a **mismatched shape** of recursive variables inside fixpoint formulas:

$$\mu X_1. (R \vee R \frown X_1) \vdash \mu X_2. (R \vee X_2 \frown R)$$



There are no rules that can perform fixpoint induction on a **mismatched shape** of recursive variables inside fixpoint formulas:

$$\mu X_1.(R \vee R \frown X_1) \vdash \mu X_2.(R \vee X_2 \frown R)$$

Solution: Synchronization

- Employment of a rule for **synchronization** between recursive variables:

$$\mu X_2.(R \vee X_2 \frown R) \rightsquigarrow \mu X_2.(R \vee R \frown X_2)$$

- **Chop formulas** are a subclass of trace formulas for fixed relation R and fixed recursive variable X generated by the following grammar:

$$\Phi ::= \Psi \mid \Psi \vee \Phi \text{ with } \Psi ::= R \mid X \mid \Psi \frown \Psi$$

- Each chop formula can be mapped onto a **context-free grammar**.

Example

$Id \frown Id \vee Id \frown X \frown Id$ is a chop formula with CFG production rule $X \rightarrow Id \ Id \mid Id \ X \ Id$

- The language specified by the context-free grammar must be **regular** (*Parikh's lemma*).
- Fixpoint (chop) formulas can be **reshaped** depending on their language:

$$\text{SYNC} \frac{\xi \diamond \Gamma \vdash \mu X. \Psi', \Delta}{\xi \diamond \Gamma \vdash \mu X. \Psi, \Delta} L(\text{Gr}(\Psi')) \subseteq L(\text{Gr}(\Psi))$$

Example

$$\text{SYNC} \frac{\mu X_1. (R \vee R \frown X_1) \vdash \mu X_2. (R \vee R \frown X_2)}{\mu X_1. (R \vee R \frown X_1) \vdash \mu X_2. (R \vee X_2 \frown R)}$$

- **Trace formulas** can be used to
 - specify programs **precisely**
 - specify **abstract** trace properties
- The **sequent calculus** for trace formula implication proves that $stf(S) \models \Phi$ with
 - **fixpoint inductions** for symbolic derivations (formalized in **Isabelle**)
 - **method contracts** for state updates over calls
 - **synchronization** for synchronizing recursive variables for fixpoint inductions
- **Soundness** of the calculus
- Future Work: Resolve **Incompleteness** of the calculus

- Formalization of the calculus achieved in theorem prover Isabelle/HOL.
- Properties can be inferred by **manual** rule application or **semi-automatic** rule application.
⇒ Invariants for fixpoint formulas need to be **manually** provided.

```
lemma "[stf S_down] ⊢ [μ ''dec''. ((Rel R_x_dec) ⊔ Rel R_x_dec ∩ RVar ''dec'')]"  
  unfolding S_down_def  
  apply simp  
  apply tfi_auto  
  apply lenr_prep_fpi  
  apply (rule FPI; auto)  
  apply tfi_auto .
```

Figure: Assume R_{x_dec} is a relation specifying that x **does not** increase.

Appendix: Calculus Rules

Relation Rules: Axiom



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- Let relation R restricted on P_Γ be

$$R|_{P_\Gamma} := \{s \cdot s' \mid R(s, s') \wedge s \models \bigwedge P_\Gamma\}$$

- The **relation rule axiom** determines if the relation of the antecedent is included in the relation of the succedent:

$$\text{REL} \frac{}{\Gamma, R \vdash R', \Delta} R|_{P_\Gamma} \subseteq R'$$

Example

$$\text{REL} \frac{}{x > 0, Sb_x^{x+1} \vdash R_{\text{pos}}} Sb_x^{x+1}|_{x>0} \subseteq R_{\text{pos}}$$

Appendix: Calculus Rules

Lengthening Rules



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- Let us define **repetitions** of a formula containing recursive variables:

$repeat_0(\Phi) := \Phi$ and $repeat_i(\Phi) := \Phi[repeat_{i-1}(\Phi)/X]$ for $i \geq 1$,

- We can use **lengthening rules** to *internally lengthen* the fixpoint formulas:

$$\text{LENL} \frac{\Gamma, \mu X. repeat_i(\Phi) \vdash \Delta}{\Gamma, \mu X. \Phi \vdash \Delta} \quad i \geq 1$$

$$\text{LENR} \frac{\Gamma \vdash \mu X. repeat_i(\Psi), \Delta}{\Gamma \vdash \mu X. \Psi, \Delta} \quad i \geq 1$$

Example

$$\text{LENR} \frac{\Gamma \vdash \mu X. (R \vee R \frown (R \vee R \frown X))}{\Gamma \vdash \mu X. (R \vee R \frown X)} \quad 1 \geq 1$$

Appendix: Fixpoint Induction

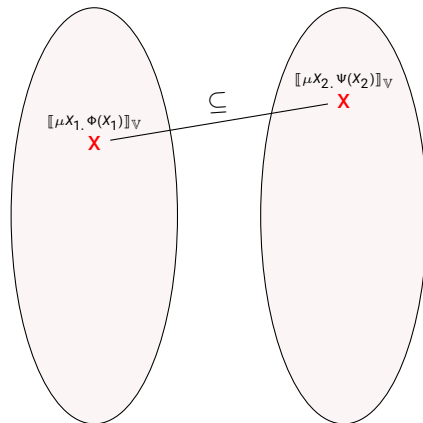
Proof Objective



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- We aim to **inductively** deduce the $\subseteq$ -inclusion of both least fixpoints.
- Based on **powerset lattice of finite traces** $P(\text{State}^+)$.

How to infer the proof objective?



Appendix: Fixpoint Induction

Induction Principle

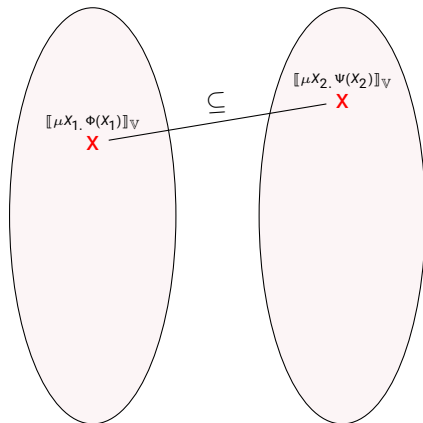


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Assumption:

For any set of finite traces $\gamma_1, \gamma_2 \in P(\text{State}^+)$ with $\gamma_1 \subseteq \gamma_2$, it holds that

$$\llbracket \Phi(X_1) \rrbracket_{\forall[X_1 \mapsto \gamma_1]} \subseteq \llbracket \Psi(X_2) \rrbracket_{\forall[X_2 \mapsto \gamma_2]}$$



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Induction Principle

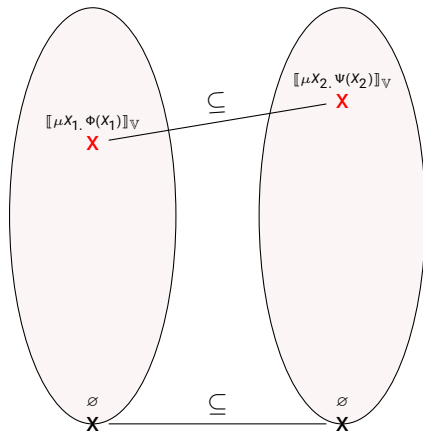


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Appendix: Fixpoint Induction

Induction Principle

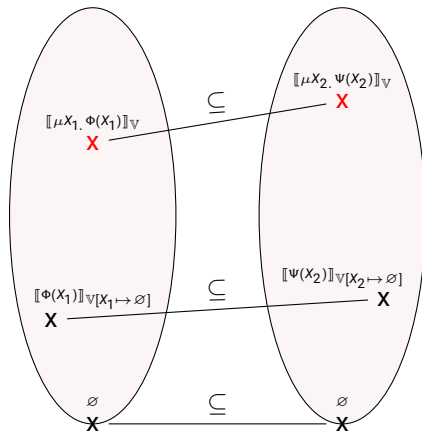


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Assumption:

For any set of finite traces $\gamma_1, \gamma_2 \in P(\text{State}^+)$ with $\gamma_1 \subseteq \gamma_2$, it holds that

$$\llbracket \Phi(X_1) \rrbracket_{V[X_1 \mapsto \gamma_1]} \subseteq \llbracket \Psi(X_2) \rrbracket_{V[X_2 \mapsto \gamma_2]}$$



Appendix: Fixpoint Induction

Induction Principle

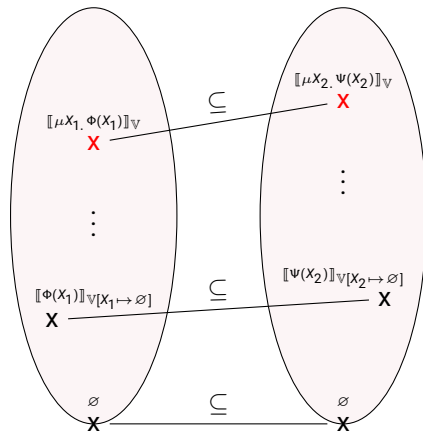


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Assumption:

For any set of finite traces $\gamma_1, \gamma_2 \in P(\text{State}^+)$ with $\gamma_1 \subseteq \gamma_2$, it holds that

$$\llbracket \Phi(X_1) \rrbracket_{V[X_1 \mapsto \gamma_1]} \subseteq \llbracket \Psi(X_2) \rrbracket_{V[X_2 \mapsto \gamma_2]}$$



Appendix: Fixpoint Induction

Induction Principle with Invariants

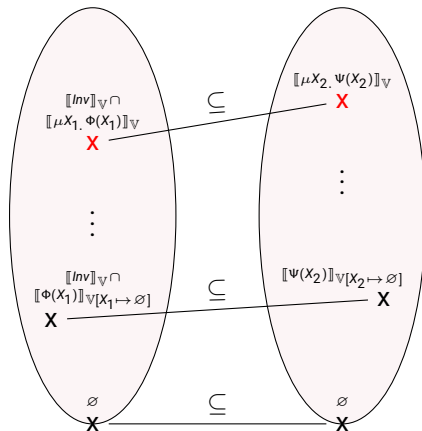


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Assumption:

For any set of finite traces $\gamma_1, \gamma_2 \in P(\text{State}^+)$ with $\llbracket \text{Inv} \rrbracket_{\forall} \cap \gamma_1 \subseteq \gamma_2$, it holds that

$$\llbracket \text{Inv} \rrbracket_{\forall} \cap \llbracket \Phi(X_1) \rrbracket_{\forall[X_1 \mapsto \gamma_1]} \subseteq \llbracket \Psi(X_2) \rrbracket_{\forall[X_2 \mapsto \gamma_2]}$$



Appendix: Calculus Rules

Method Contract Rules



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$$\text{MC} \frac{v_{old}^i \in \text{fresh}(\text{Var}) \quad \mathbb{C}' = \mathbb{C}[m \mapsto (pre, post)] \quad \xi \diamond \langle pre(\Phi) \rangle \vdash_{\mathbb{C}'} \langle post(\Phi) \rangle \quad \xi \diamond \Gamma, \mu X_m. \Phi \vdash_{\mathbb{C}'} \Delta}{\xi \diamond \Gamma, \mu X_m. \Phi \vdash_{\mathbb{C}} \Delta}$$

$$\text{CH-RVAR} \frac{\mathbb{C}(m) = (pre, post) \quad P_{\Gamma} \vdash_{\mathbb{C}} p \wedge pre \quad \xi \diamond P_{\Gamma}[v_{old}^i/v^i], post, \Phi \vdash_{\mathbb{C}} \Psi}{\xi, (X_m|_p, X) \diamond \Gamma, X_m \frown \Phi \vdash_{\mathbb{C}} X \frown \Psi, \Delta}$$

$$\text{CH-FPI} \frac{\mathbb{C}(m) = (pre, post) \quad P_{\Gamma} \vdash_{\mathbb{C}} I \wedge pre \quad \xi, (X_m|_I, X) \diamond I, \Phi_1 \vdash_{\mathbb{C}} \Psi_1 \quad \xi \diamond P_{\Gamma}[v_{old}^i/v^i], post, \Phi_2 \vdash_{\mathbb{C}} \Psi_2}{\xi \diamond \Gamma, (\mu X_m. \Phi_1) \frown \Phi_2 \vdash_{\mathbb{C}} (\mu X. \Psi_1) \frown \Psi_2, \Delta}$$