

A Formal Model for Direct-style Asynchronous Observables

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27th Nordic Workshop on Programming Theory (NWPT)
Reykjavik University, Iceland, 21-23 October 2015



Context: Asynchronous Programming

- Thread-based, blocking abstractions
 - Direct-style programming model (easy of use), good debugging support
 - Not efficient, not scalable
- Event-based, non-blocking abstractions
 - Efficient, scalable
 - Hard to use: inversion of control, “callback hell”
 - Debugging support lacking

Background: Async Model

- A recent proposal for simplifying asynchronous programming
- Essence of the Async Model:
 1. A way to spawn an asynchronous computation (*async*), returning a (first-class) future
 2. A way to suspend an asynchronous computation (*await*) until a future is completed
- Result: a *direct-style API for non-blocking futures*
- Practical relevance: F#, C# 5.0, Scala 2.11

Example

- Setting: Play Web Framework
- Task: Given two web service requests, when both are completed, return response that combines both results:

```
val futureDOY: Future[Response] =  
  WS.url("http://api.day-of-year/today").get  
val futureDaysLeft: Future[Response] =  
  WS.url("http://api.days-left/today").get
```

Example

Using Scala Async

```
val respFut = async {  
  val dayOfYear = await(futureDOY).body  
  val daysLeft = await(futureDaysLeft).body  
  Ok("" + dayOfYear + ": " + daysLeft + " days left!")  
}
```

Example

Using plain Scala futures

```
futureDOY.flatMap { doyResponse =>
  val dayOfYear = doyResponse.body
  futureDaysLeft.map { daysLeftResponse =>
    val daysLeft = daysLeftResponse.body
    Ok("" + dayOfYear + ": " + daysLeft + " days left!")
  }
}
```

Using Scala Async

```
val respFut = async {
  val dayOfYear = await(futureDOY).body
  val daysLeft = await(futureDaysLeft).body
  Ok("" + dayOfYear + ": " + daysLeft + " days left!")
}
```

Problem

- Async model only supports futures
- What about streams of asynchronous events?

Asynchronous Streams

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- Requirement: ***extreme scalability and efficiency***
 - Precludes future-per-event implementations
 - Examples: Netflix, Samsung SAMI, ...

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- Popular programming model: Reactive Extensions
 - Based on the duality of iterators and observers

Reactive Extensions: Essence

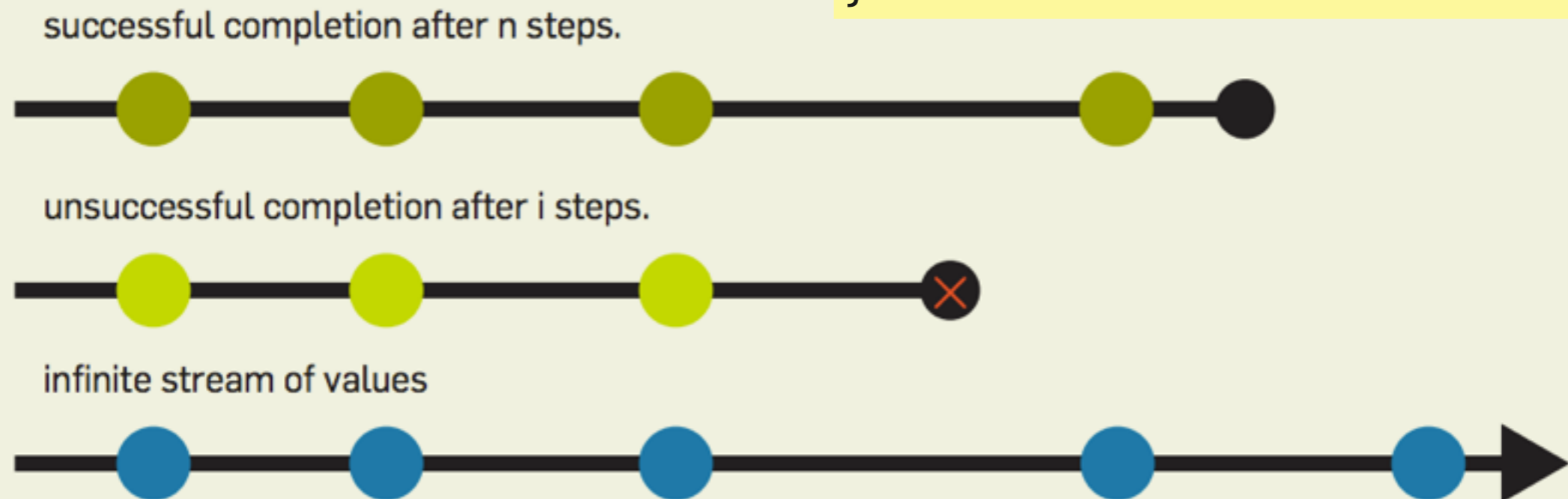
```
trait Observable[T] {  
  def subscribe(obs: Observer[T]): Closable  
}
```

```
trait Observer[T] {  
  def onNext(v: T): Unit  
  def onFailure(t: Throwable): Unit  
  def onDone(): Unit  
}
```

Observer[T]: Interactions

```
trait Observer[T] {  
  def onNext(v: T): Unit  
  def onFailure(t: Throwable): Unit  
  def onDone(): Unit  
}
```

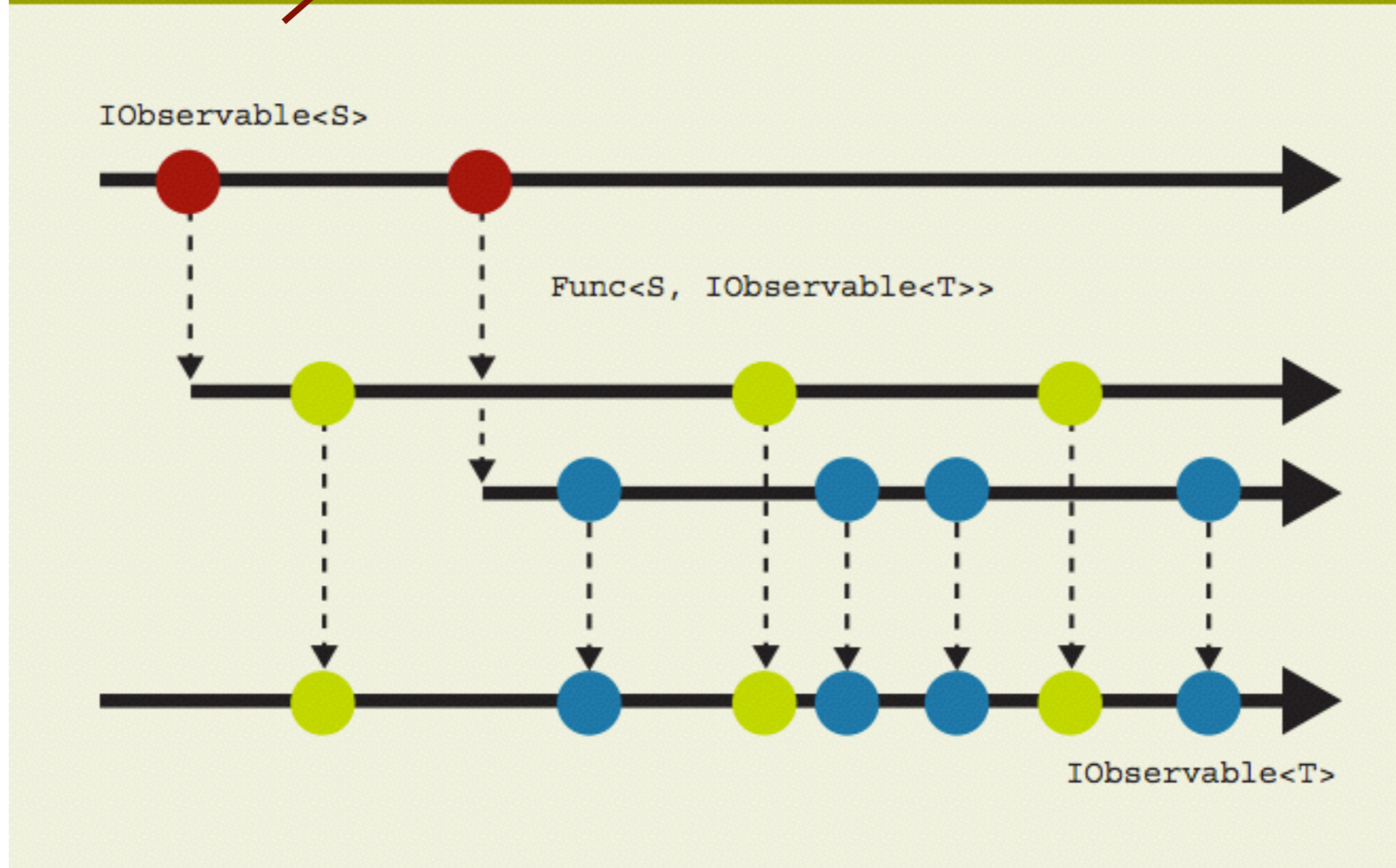
Figure 3. Possible sequences of interaction when using Observer[T]



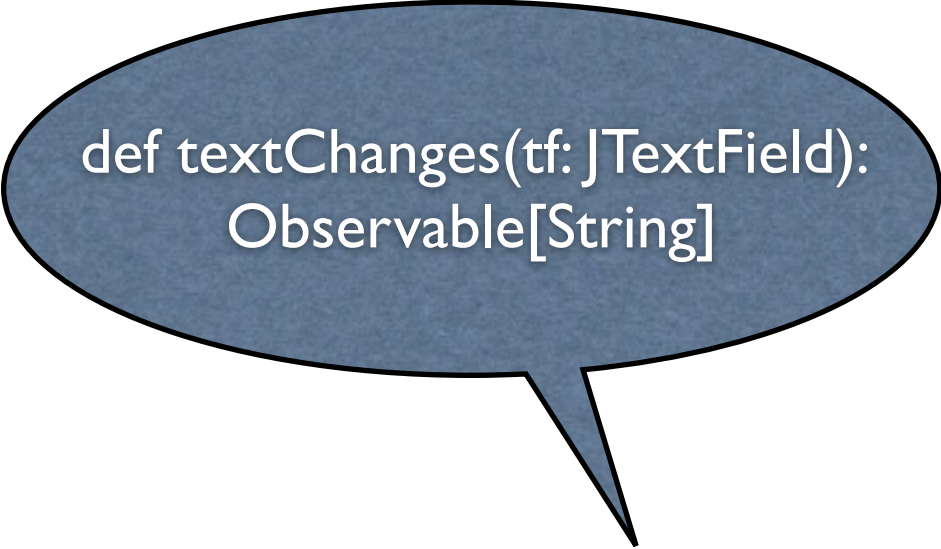
The Real Power: Combinators

flatMap

Figure 7. The SelectMany operator.



Combinators: Example



```
def textChanges(tf: JTextField):  
  Observable[String]
```

```
textChanges(textField)  
  .flatMap(word => completions(word))  
  .subscribe(observeChanges(output))
```



```
Observable[String]
```

Problem

- Programming with reactive streams suffers from an inversion of control
- Requires explicit programming in continuation-passing style (CPS)
- Writing stateful combinators is difficult

RAY: Idea

- Unify Reactive Extensions and Async
- Introduce variant of `async { }` to create observables instead of futures: `rasync { }`
- Within `rasync { }`: enable *awaiting events of observables in direct-style*
- Create observables by yielding events from within `rasync { }`

RAY: Primitives

- `rasync[T] { }` - create `Observable[T]`
- `awaitNextOrDone(obs)` - awaits and returns `Some(next event of obs)`, or else returns `None` if `obs` has terminated
- `yieldNext(evt)` - yields next event of current observable

RAY: Simple Example

```
val forwarder = rasync[Int] {  
  var next: Option[Int] = awaitNextOrDone(stream)  
  while (next.nonEmpty) {  
    yieldNext(next)  
    next = awaitNextOrDone(stream)  
  }  
}
```

Formalization

Object-based calculus

$p ::= \overline{cd} e$	program
$cd ::= \text{class } C \{ \overline{fd} \overline{md} \}$	class declaration
$fd ::= \text{var } f : \sigma$	field declaration
$md ::= \text{def } m(\overline{x : \sigma}) : \tau = e$	method declaration
$\sigma, \tau ::=$	type
γ	value type
ρ	reference type
$\gamma ::=$	value type
Boolean	boolean
Int	integer
$\rho ::=$	reference type
C	class type
Observable $[\sigma]$	observable type

Expressions

$e ::=$	expressions
\underline{b}	boolean
\underline{i}	integer
x	variable
<code>null</code>	null
<code>if</code> (x) { e } <code>else</code> { e' }	condition
<code>while</code> (x) { e }	while loop
$x.f$	selection
$x.f = y$	assignment
$x.m(\bar{y})$	invocation
<code>new</code> $C(\bar{y})$	instance creation
<code>let</code> $x = e$ <code>in</code> e'	let binding
<code>rasync</code> [σ] (\bar{y}) { e }	observable creation
<code>await</code> (x)	await next event
<code>yield</code> (x)	yield event

Expressions

$e ::=$	expressions
\underline{b}	boolean
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x	variable
<code>null</code>	null
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<code>new C(\bar{y})</code>	instance creation
<code>let x = e in e'</code>	let binding
<code>rasync[σ](\bar{y}) {e}</code>	observable creation
<code>await(x)</code>	await next event
<code>yield(x)</code>	yield event

Operational Semantics

- Small-step operational semantics
- Transitions for frames, frame stacks, and processes (sets of frame stacks)

$$\frac{H(L(y)) = \langle \rho, FM \rangle}{H, \langle L, \text{let } x = y.f \text{ in } e \rangle^l \longrightarrow H, \langle L[x \mapsto FM(f)], e \rangle^l} \quad (\text{E-FIELD})$$

$$\frac{\begin{array}{l} \text{fields}(C) = \bar{f} \quad o \notin \text{dom}(H) \\ H' = H[o \mapsto \langle C, \bar{f} \mapsto L(\bar{y}) \rangle] \end{array}}{H, \langle L, \text{let } x = \text{new } C(\bar{y}) \text{ in } e \rangle^l \longrightarrow H', \langle L[x \mapsto o], e \rangle^l} \quad (\text{E-NEW})$$

Reducing Frame Stacks

$$\frac{\begin{array}{l} H(L(y)) = \langle \rho, FM \rangle \quad mbody(\rho, m) = (\bar{x}) \rightarrow e' \\ L' = [\bar{x} \mapsto L(\bar{z}), \mathbf{this} \mapsto L(y)] \end{array}}{H, \langle L, \mathbf{let } x = y.m(\bar{z}) \mathbf{ in } e \rangle^l \circ FS \rightarrow H, \langle L', e' \rangle^s \circ \langle L, e \rangle_x^l \circ FS} \quad (\text{E-METHOD})$$

$$\frac{}{H, \langle L, y \rangle^s \circ \langle L', e \rangle_x^l \circ FS \rightarrow H, \langle L'[x \mapsto L(y)], e \rangle^l \circ FS} \quad (\text{E-RETURN})$$

$$\frac{H, F \rightarrow H', F'}{H, F \circ FS \rightarrow H', F' \circ FS} \quad (\text{E-FRAME})$$

Observables

- A special kind of object
- State of an observable: running or done

$$H(o) = \langle \mathbf{Observable}[\sigma], \mathit{running}(\bar{F}, \bar{S}) \rangle$$

- Initial state: $\mathit{running}(\epsilon, \epsilon)$
- Running state: $\mathit{running}(\bar{F}, \bar{S})$
- Terminated state: $\mathit{done}(\bar{S})$

Waiters

$$H(o) = \langle \text{Observable}[\sigma], \text{running}(\bar{F}, \bar{S}) \rangle$$

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- **Waiters:** asynchronous frames of suspended observables
- Example of a waiter:

$$F = \langle L, \text{let } x = \text{await}(y) \text{ in } t \rangle^{a(o, \bar{p})}$$

Heap Evolution

Heap Evolution property formalizes ***permitted observable protocol state transitions***

Definition 1 (Heap Evolution). Heap H evolves to H' wrt a set of observable ids B , written $H \leq_B H'$ if

- (i) $\forall o \in \text{dom}(H')$. if $o \notin \text{dom}(H)$ and $H'(o) = \langle \psi, \text{running}(\bar{F}, \bar{S}) \rangle$ then $\bar{F} = \bar{S} = \epsilon$, and
- (ii) $\forall o \in \text{dom}(H)$.
 - if $H(o) = \langle C, FM \rangle$ then $H'(o) = \langle C, FM' \rangle$,
 - if $H(o) = \langle \psi, \text{done}(\bar{S}) \rangle$ then $H'(o) = \langle \psi, \text{done}(\bar{R} \uplus \{ \langle o', q' \rangle \}) \rangle$ where $\bar{S} = \bar{R} \uplus \{ \langle o', q \rangle \}$, and
 - if $H(o) = \langle \psi, \text{running}(\bar{F}, \bar{S}) \rangle$ then $H'(o) = \langle \psi, \text{running}(\bar{F}, \bar{S} \uplus \{ \langle o, [] \rangle \}) \rangle$ or $(H'(o) = \langle \psi, \text{running}(\epsilon, \bar{R}) \rangle$ and $\text{dom}(\bar{S}) = \text{dom}(\bar{R}))$ or $(H'(o) = \langle \psi, \text{running}(\bar{F} \cup \bar{G}, \bar{S}) \rangle$, $\text{obsIds}(\bar{F}) \# \text{obsIds}(\bar{G})$ and $\text{obsIds}(\bar{G}) \subseteq B)$ or $H'(o) = \langle \psi, \text{done}(\bar{S}) \rangle$.

Example: Terminating an Observable

$$\begin{array}{l}
 H(o) = \langle \text{Observable}[\sigma], \text{running}(\bar{F}, \bar{S}) \rangle \\
 \bar{R} = \text{resume}(\bar{F}, \text{None}) \quad Q = \{R \circ \epsilon \mid R \in \bar{R}\} \\
 H_0 = H[o \mapsto \langle \text{Observable}[\sigma], \text{done}(\bar{S}) \rangle] \\
 \forall i \in 1 \dots n. H_i = H_{i-1}[p_i \mapsto \text{unsub}(o, p_i, H)] \\
 \hline
 H, \{ \langle L, x \rangle^{a(o, \bar{p})} \circ FS \} \cup P \rightsquigarrow H_n, \{ FS \} \cup P \cup Q \quad (\text{E-RASYNC-RETURN})
 \end{array}$$

Example: Terminating an Observable

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 H, \{ \langle L, x \rangle^{a(o, \bar{p})} \circ FS \} \cup P \rightsquigarrow H_n, \{ FS \} \cup P \cup Q \quad (\text{E-RASYNC-RETURN})
 \end{array}$$

Preservation of Heap Evolution

- Proving that reduction preserves heap evolution requires preserving ***non-interference properties***
- Example: a given observable o can only be waiting for exactly one other observable
- Requires observable ids of waiters to be distinct

Subject Reduction

Subject reduction theorem

- ensures ***observable protocol***
- through ***heap evolution*** and ***non-interference***

Theorem 1 (Subject Reduction). *If $\vdash H : \star$ and $\vdash H \text{ ok}$ then:*

1. *If $H \vdash F : \sigma$, $H \vdash F \text{ ok}$ and $H, F \longrightarrow H', F'$ then $\vdash H' : \star$, $\vdash H' \text{ ok}$, $H' \vdash F' : \sigma$, $H' \vdash F' \text{ ok}$, and $\forall B. H \leq_B H'$.*
2. *If $H \vdash FS : \sigma$, $H \vdash FS \text{ ok}$ and $H, FS \twoheadrightarrow H', FS'$ then $\vdash H' : \star$, $\vdash H' \text{ ok}$, $H' \vdash FS' : \sigma$, $H' \vdash FS' \text{ ok}$ and $H \leq_{\text{obsIds}(FS)} H'$.*
3. *If $H \vdash P : \star$, $H \vdash P \text{ ok}$ and $H, P \rightsquigarrow H', P'$ then $\vdash H' : \star$, $\vdash H' \text{ ok}$, $H' \vdash P' : \star$ and $H' \vdash P' \text{ ok}$.*

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2. *If $H \vdash FS : \sigma$, $H \vdash FS \text{ ok}$ and $H, FS \twoheadrightarrow H', FS'$ then $\vdash H' : \star$, $\vdash H' \text{ ok}$, $H' \vdash FS' : \sigma$, $H' \vdash FS' \text{ ok}$ and $H \leq_{\text{obsIds}(FS)} H'$.*
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3. *If $H \vdash P : \star$, $H \vdash P \text{ ok}$ and $H, P \rightsquigarrow H', P'$ then $\vdash H' : \star$, $\vdash H' \text{ ok}$, $H' \vdash P' : \star$ and $H' \vdash P' \text{ ok}$.*

Selected Related Work

- Bierman et al. *Pause 'n' Play: Formalizing Asynchronous C#*. ECOOP 2012
- Meijer, Millikin, Bracha. *Spicing Up Dart with Side Effects*. ACM Queue 13.3, 2015
- Meijer. *Your mouse is a database*. CACM 55.5, 2012
- Syme, Petricek, Lomov. *The F# Asynchronous Programming Model*. PADL 2011

Results

- RAY: unifies Async model and Reactive Extensions
- Operational semantics and static type system
- Proof of subject reduction
 - Based on non-interference properties
 - Ensures observable protocol
- Companion technical report provides details
- See <http://www.csc.kth.se/~phaller/nwpt2015/>

Thank you!

Results

Questions?

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