

# Towards Small-step Compilation Schemas for SOS

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# What?

## Motivation

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$$\rho \vdash t \xrightarrow{\ell} t'$$

$$\rho \vdash \mathbf{print}(t) \xrightarrow{\ell} \mathbf{print}(t')$$

Value  $v$

$$\rho \vdash \mathbf{print}(v) \xrightarrow{\text{out } v} v$$

$$\rho \vdash e \xrightarrow{\ell} e'$$

$$\rho \vdash \mathbf{if}(e, s, t) \xrightarrow{\ell} \mathbf{if}(e', s, t)$$

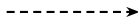
$$\rho \vdash \mathbf{if}(\mathbf{true}, s, t) \xrightarrow{\tau} s$$

$$\rho \vdash \mathbf{if}(\mathbf{false}, s, t) \xrightarrow{\tau} t$$

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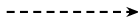
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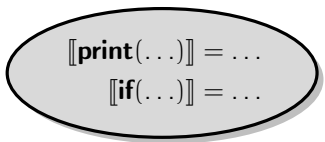
$\llbracket \mathbf{print}(\dots) \rrbracket = \dots$   
 $\llbracket \mathbf{if}(\dots) \rrbracket = \dots$

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`if(true, print("a"), print("b"))`



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`if(true, print("a"), print("b"))`

`[[print(...)] = ...`  
`[[if(...)] = ...`

```
1 if0:
2   %tmp0 ← 1
3   case %tmp0 2
4   jump if1_0
5   jump if1_1
6   halt
7 if1_0:
8   %tmp1 ← "b"
9   out %tmp1
10  jump tmp3
11 if1_1:
12   %tmp2 ← "a"
13   out %tmp2
14   jump tmp3
15 tmp3:
16   %tmp3 ←
17   phi %tmp1 %tmp2
18   halt
```

# How?

## Overview of the idea

- translate steps of open terms
- 1 abstract state  $\approx$  1 block
- *atomic* blocks
- block might contain many instructions
- terminated by jumps or a halt
- non-determinism in semantics – non-deterministic schema

# Basic Examples

## Printing stuff

Consider **print**:

$$\frac{\rho \vdash t \xrightarrow{\ell} t'}{\rho \vdash \mathbf{print}(t) \xrightarrow{\ell} \mathbf{print}(t')}$$

$$\frac{\text{Value } v}{\rho \vdash \mathbf{print}(v) \xrightarrow{\text{out } v} v}$$

If there is a sequence of  $n$  transitions for a term  $t$  (actually  $\langle \rho, t \rangle$ ):

$$t \xrightarrow{\ell_1} \dots \xrightarrow{\ell_{n-1}} t_{n-1} \xrightarrow{\ell_n} v$$

then the computation of **print**( $t$ ) proceeds as follows:

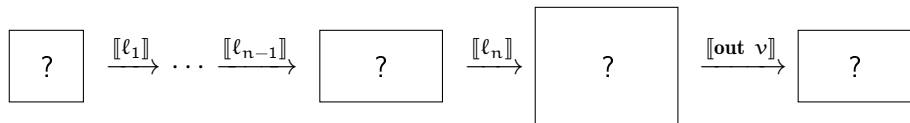
$$\mathbf{print}(t) \xrightarrow{\ell_1} \dots \xrightarrow{\ell_{n-1}} \mathbf{print}(t_{n-1}) \xrightarrow{\ell_n} \mathbf{print}(v) \xrightarrow{\text{out } v} v$$



# Basic Examples

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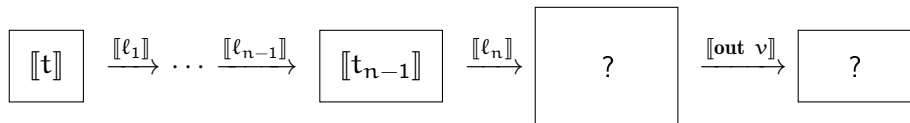
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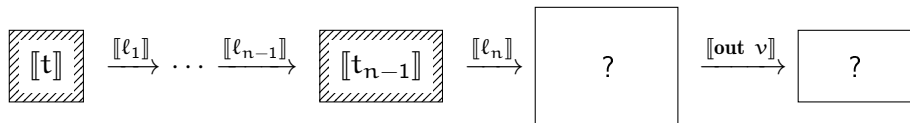
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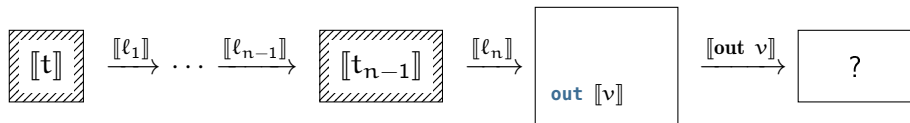
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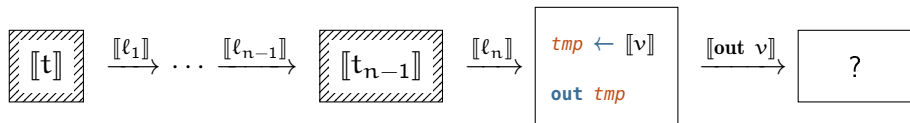
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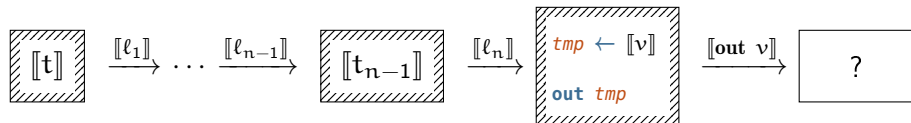
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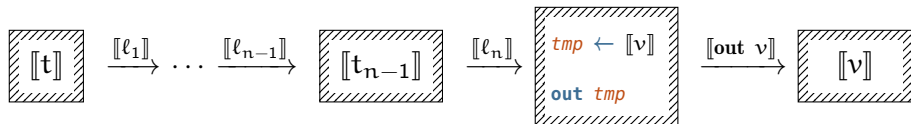
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# Basic Examples

## Schema for print

Schema defined in terms of *translators*:

- operations: code, next, label, jumps
- translators have states
  - ▶ correspond to one or more states of SOS computation
- e.g., translator for **print**:  $\text{tr}_{\text{print}}$
- translator state:  $\llbracket \text{print}(t) \rrbracket = \text{tr}_{\text{print}}(\llbracket t \rrbracket)$



# Basic Examples

## Schema for print

$$\frac{\rho \vdash t \xrightarrow{\ell} t'}{\rho \vdash \mathbf{print}(t) \xrightarrow{\ell} \mathbf{print}(t')}$$

$$\frac{\text{Value } v}{\rho \vdash \mathbf{print}(v) \xrightarrow{\text{out } v} v}$$

$$\text{code}[\mathbf{print}(t)] = \begin{cases} \text{code}[\llbracket t \rrbracket] & \text{if } \text{next}[\llbracket t \rrbracket] \neq \text{none} \\ \text{code}[\llbracket t \rrbracket] \cdot \mathbf{out} \text{ label}[\llbracket t \rrbracket] & \text{if } \text{next}[\llbracket t \rrbracket] = \text{none} \end{cases}$$

$$\text{next}[\mathbf{print}(t)] = \begin{cases} \text{tr}_{\mathbf{print}}(\text{next}[\llbracket t \rrbracket]) & \text{if } \text{next}[\llbracket t \rrbracket] \neq \text{none} \\ \llbracket t \rrbracket & \text{if } \text{next}[\llbracket t \rrbracket] = \text{none} \end{cases}$$

# Basic Examples

## Let-bindings

$$\frac{\rho \vdash t_1 \xrightarrow{\ell} t'_1}{\rho \vdash \mathbf{let}(i, t_1, t_2) \xrightarrow{\ell} \mathbf{let}(i, t'_1, t_2)}$$

$$\frac{\text{Value } v_1 \quad \rho[i \mapsto v_1] \vdash t_2 \xrightarrow{\ell} t'_2}{\rho \vdash \mathbf{let}(i, v_1, t_2) \xrightarrow{\ell} \mathbf{let}(i, v_1, t'_2)}$$

$$\frac{\text{Value } v_1 \quad \text{Value } v_2}{\rho \vdash \mathbf{let}(i, v_1, v_2) \xrightarrow{\tau} v_2}$$

# Basic Examples

## Let-bindings

code[[let(i, t<sub>1</sub>, t<sub>2</sub>)] =

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$\text{code}[\llbracket \text{let}(i, t_1, t_2) \rrbracket] =$

①  $\text{code}[\llbracket t_1 \rrbracket]$

▶ if  $\text{next}[\llbracket t_1 \rrbracket] \neq \text{none}$

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②  $\text{code } tr_{iv} \cdot \text{push\_env } tmp \cdot \text{code}[\llbracket t_2 \rrbracket] \cdot \text{pop\_env}$

▶ if  $\text{next}[\llbracket t_1 \rrbracket] = \text{none}$  and  $\text{next}[\llbracket t_2 \rrbracket] \neq \text{none}$ ,

▶  $tr_{iv} = \llbracket \{i \mapsto t_1\} \rrbracket$ ,

▶  $tmp = \text{label}(tr_{iv})$

$$\frac{\text{Value } v_1 \quad \rho[i \mapsto v_1] \vdash t_2 \xrightarrow{\ell} t'_2}{\rho \vdash \text{let}(i, v_1, t_2) \xrightarrow{\ell} \text{let}(i, v_1, t'_2)}$$

# Basic Examples

## Let-bindings

code[[let(i, t<sub>1</sub>, t<sub>2</sub>)] =

① code[[t<sub>1</sub>]]

▶ if next[[t<sub>1</sub>]] ≠ none

② code *tr<sub>iv</sub>* • **push\_env** *tmp* • code[[t<sub>2</sub>]] • **pop\_env**

▶ if next[[t<sub>1</sub>]] = none and next[[t<sub>2</sub>]] ≠ none,

▶ *tr<sub>iv</sub>* = [[{i ↦ t<sub>1</sub>}],

▶ *tmp* = label(*tr<sub>iv</sub>*)

$$\frac{\text{Value } v_1 \quad \rho[i \mapsto v_1] \vdash t_2 \xrightarrow{\ell} t'_2}{\rho \vdash \text{let}(i, v_1, t_2) \xrightarrow{\ell} \text{let}(i, v_1, t'_2)}$$

*name of temporary holding the binding*

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*name of temporary holding the binding*

③  $\varepsilon$

- ▶ if  $\text{next}[\llbracket t_1 \rrbracket] \neq \text{none}$  and  $\text{next}[\llbracket t_2 \rrbracket] \neq \text{none}$
- ▶ also:  $\text{next}[\llbracket \text{let}(i, t_1, t_2) \rrbracket] = \llbracket t_2 \rrbracket$  and  
 $\text{jumps}[\llbracket \text{let}(i, t_1, t_2) \rrbracket] = \text{jump } \text{label}[\llbracket t_2 \rrbracket]$

Value  $v_1$

Value  $v_2$

$\rho \vdash \text{let}(i, v_1, v_2) \xrightarrow{\tau} v_2$

# Top-level Translator

- translating the top-level phrase
- invoke translator for the outermost construct
- push jumps to the end
  - ▶ exit point should be at the end block
- if no jumps – final state – issue **halt**



# Conditional Branching

- for conditionals – need to translate both branches and join them

$$\frac{\rho \vdash e \xrightarrow{\ell} e'}{\rho \vdash \text{if}(e, s, t) \xrightarrow{\ell} \text{if}(e', s, t)}$$
$$\frac{}{\rho \vdash \text{if}(\text{true}, s, t) \xrightarrow{\tau} s} \quad \frac{}{\rho \vdash \text{if}(\text{false}, s, t) \xrightarrow{\tau} t}$$

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$\llbracket e \rrbracket$

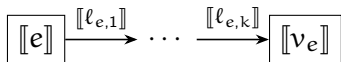
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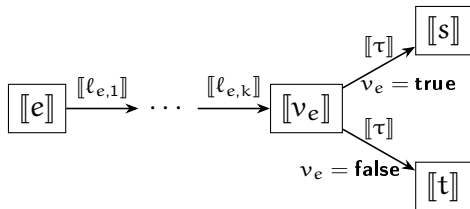
$$\llbracket e \rrbracket \xrightarrow{\llbracket \ell_{e,1} \rrbracket} \dots$$

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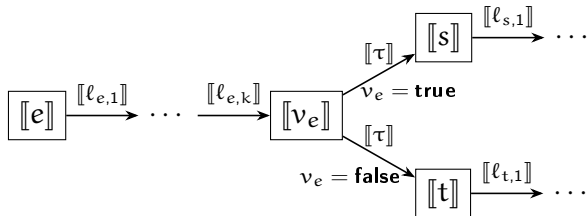
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# Conditional Branching

$$(s \xrightarrow{\ell} s')$$

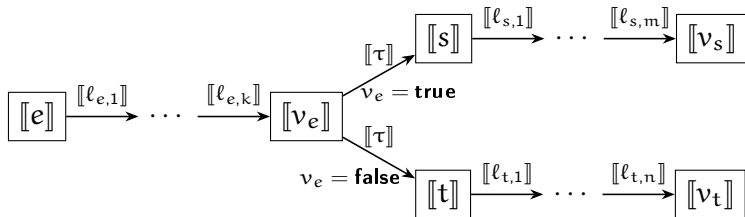
$$(t \xrightarrow{\ell} t')$$



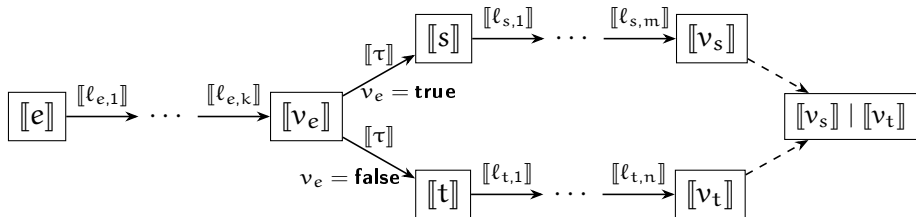
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$$(s \xrightarrow{\ell} s')$$

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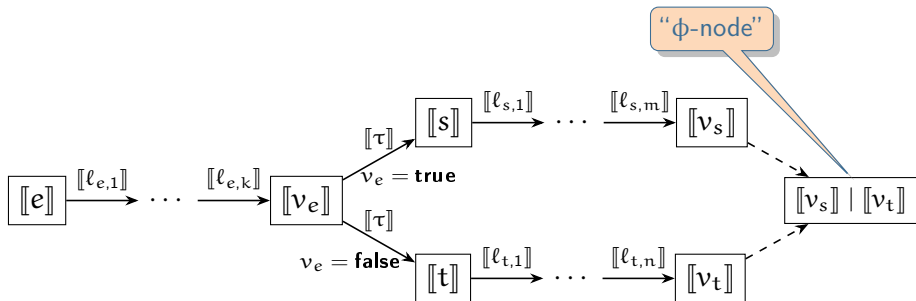


# Conditional Branching





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# An Example Translation

```
if(true, print("a"), print("b"))
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```
if0:  
  %tmp0 ← 1 ; [[true]]  
  case %tmp0 2 ; pc ← pc + min(%tmp0, 2) + 1  
  jump if1_0 ; [[false]] branch  
  jump if1_1 ; [[true]] branch  
  halt ; otherwise: stuck
```

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`if(true, print("a"), print("b"))`

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if0:
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  jump if1_1 ; [[true]] branch
  halt ; otherwise: stuck
```

```
if1_0: ; [[print("b")]]
  %tmp1 ← "b" ; [["b"]]
  out %tmp1
  jump tmp1

tmp1: ; [["b"]]
  jump tmp3
```

```
if1_1: ; [[print("a")]]
  %tmp2 ← "a" ; [["a"]]
  out %tmp2
  jump tmp2

tmp2: ; [["a"]]
  jump tmp3
```

# An Example Translation

`if(true, print("a"), print("b"))`

```
if0:
  %tmp0 ← 1 ; [[true]]
  case %tmp0 2 ; pc ← pc + min(%tmp0, 2) + 1
  jump if1_0 ; [[false]] branch
  jump if1_1 ; [[true]] branch
  halt ; otherwise: stuck
```

```
if1_0: ; [[print("b")]]
  %tmp1 ← "b" ; [[b]]
  out %tmp1
  jump tmp1

tmp1: ; ["b"]
  jump tmp3
```

```
if1_1: ; [[print("a")]]
  %tmp2 ← "a" ; [[a]]
  out %tmp2
  jump tmp2

tmp2: ; ["a"]
  jump tmp3
```

```
tmp3: ; ["b"] | ["a"]
  %tmp3 ← phi %tmp1 %tmp2
  halt ; finished
```

# Non-determinism

$$\frac{s \xrightarrow{\ell} s'}{\text{inter}(s, t) \xrightarrow{\ell} \text{inter}(s', t)} \quad \frac{t \xrightarrow{\ell} t'}{\text{inter}(s, t) \xrightarrow{\ell} \text{inter}(s, t')}$$

- compile interleavings:

$$\llbracket \text{inter}(s, t) \rrbracket = \llbracket \text{inter}(s, t) \rrbracket_{\text{l}} \text{ OR } \llbracket \text{inter}(s, t) \rrbracket_{\text{r}}$$

where

$$\text{code} \llbracket \text{inter}(s, t) \rrbracket_{\text{l}} = \text{code} \llbracket s \rrbracket$$

$$\text{code} \llbracket \text{inter}(s, t) \rrbracket_{\text{r}} = \text{code} \llbracket t \rrbracket$$

$$\text{next} \llbracket \text{inter}(s, t) \rrbracket_{\text{l}} = \text{tr}_{\text{inter}}(\text{next} \llbracket s \rrbracket, \llbracket t \rrbracket) \quad \text{next} \llbracket \text{inter}(s, t) \rrbracket_{\text{r}} = \text{tr}_{\text{inter}}(\llbracket s \rrbracket, \text{next} \llbracket t \rrbracket)$$

# Iteration

Need to avoid unfolding loops:

- **while**(b, t) may end up after  $n$  steps in **while**(b, t) again:

$$\mathbf{while}(b, t) \xrightarrow{\ell_1} \dots \xrightarrow{\ell_n} \mathbf{while}(b, t)$$

- corresponds to a jump back to the first block
- but: loops cannot be interleaved

# Some Related Work

- calculation (equational derivation) of compilers (Bahr and Hutton, *JFP*, 2015)
- compilation of Esterel and Joy
  - ▶ into hardware circuits: Esterel (Berry, Sadhana, 1992), Joy (Weber et al., *REX Workshop*, 1993)
  - ▶ into sequential code: Esterel (Edwards, *CODES*, 1999)
  - ▶ correctness based on SOS semantics



# Summary

- idea: compile small-steps into atomic blocks
- each block: execution corresponds to state transition
- non-deterministic compilation schema
- future work:
  - ▶ prototype implementation, correctness, optimisation, automation

